# Wieler Solenoids from Flat Manifolds Part 2: The Unstable Groupoid

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## Acknowledgments

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#### Flat Manifold Inverse Limits

Let Y be a flat d-manifold and g a locally expansive n-fold cover. Let  $(X,\varphi)=\varliminf(Y,g),$  i.e.

$$X = \{(y_0, y_1, \dots) | y_i \in Y, g(y_{i+1}) = y_i\}$$

$$\varphi((y_0, y_1, y_2, \dots)) = (g(y_0), g(y_1), g(y_2), \dots) = (g(y_0), y_0, y_1, \dots)$$

$$\varphi^{-1}(y_0, y_1, y_2, \dots) = (y_1, y_2, \dots)$$

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Given  $x, y \in X$ , we say  $x \sim_u y$  are **unstably equivalent** if  $\lim_{n\to\infty} d(\varphi^{-n}(x), \varphi^{-n}(y)) = 0$ 

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- The "only if" direction is the result of the local expansiveness of g.
- Intuitively, we must eventually "choose the same pre-image."

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#### Definition (Unstable Groupoid)

$$\mathcal{G}_u = \{(x, y) | x \sim_u y, x, y \in X^s((z, z, z, \ldots), \varepsilon)\}$$

where z is the fixed point of g.

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- Note,  $(X, \varphi)$  has fixed point  $(1, 1, 1, \ldots)$
- Then,

$$\mathcal{G}_u(X,\varphi) = \{(x,y)|x \sim_u y, x, y \in X^s((1,1,1,\ldots),\varepsilon)\}$$

where

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• Given  $(x, y) \in X^s((1, 1, ...), \varepsilon) \times X^s((1, 1, 1, ...), \varepsilon), x \sim_u y$  if and only if for each  $\varepsilon > 0$ , there is an N such that for all  $n \geq N, d(x_n, y_n) < \varepsilon$ .

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- Recall the full 2-shift  $(\Sigma_{\{0,1\}}, \sigma)$  of two-sided binary sequences with the map:  $\sigma((x_n))_k = x_{k+1}$
- We can characterize  $G_u$  using the Markov partition,

$$\pi: (\Sigma_{\{0,1\}}, \sigma) o \varprojlim (\mathbb{R}/\mathbb{Z}, z \mapsto 2z)$$

$$\pi(\ldots x_{-2}x_{-1}.x_0x_1x_2\ldots) = (.x_{-1}x_{-2}\ldots,.x_0x_{-1}x_{-2}\ldots,.x_1x_0x_{-1}x_{-2}\ldots)$$

- If  $x = (0, .z_0, .z_1z_0, .z_2z_1z_0, ...)$  and  $y = (0, .w_0, .w_1w_0, .w_2w_1w_0, ...)$  represented in binary then  $x \sim_u y$  if and only either:
  - **1** For some  $K, z_k = w_k$  for all  $k \ge K$ .
  - 2 For some  $K, z_k(w_k) = 0$  for all  $k \ge K$  and  $w_k(z_k) = 1$ , for all  $k \ge K$ .

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# Motivating Example

• If  $Y = \mathbf{S}^1$ ,  $G = \mathbb{Z}$ , and  $g(z) = z^2$ , then  $g_*(\mathbb{Z}) = 2\mathbb{Z}$ ,  $= g_*^j(\mathbb{Z}) = 2^j\mathbb{Z}$ , and  $G/G_i = \mathbb{Z}/2^j\mathbb{Z}$ .

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- The associated odometer is:

$$\begin{split} \mathbb{Z} \curvearrowright & (\varprojlim(\mathbb{Z}/2^j\mathbb{Z}, \mathsf{coset inclusion}) \\ &= \mathbb{Z} \curvearrowright (\mathbb{Z}/\mathbb{Z} \leftarrow \mathbb{Z}/2\mathbb{Z} \leftarrow \mathbb{Z}/4\mathbb{Z} \leftarrow \mathbb{Z}/8\mathbb{Z} \leftarrow \cdots \cong \mathbb{Z}_2). \end{split}$$

### Example cont

Representing the cosets in binary, we have:

$$\label{eq:Z2Z} \begin{split} \mathbb{Z}/2\mathbb{Z} &= \{0,1\}, \ \mathbb{Z}/4\mathbb{Z} = \{00,10,01,11\}, \\ \mathbb{Z}/8\mathbb{Z} &= \{000,100,010,110,\ldots\} \text{etc.}, \end{split}$$

so that

$$\mathbb{Z}_2 = (x_0, x_0 x_1, x_0 x_1 x_2, \ldots)$$

for  $x_i \in \{0,1\}$  and the generator  $1 \in \pi_1(Y) \cong \mathbb{Z}$  acts on  $\mathbb{Z}_2$  by

$$1 \cdot (x_0 + 2\mathbb{Z}, x_0 x_1 + 4\mathbb{Z}, x_0 x_1 x_2 + 8\mathbb{Z}, \dots) =$$

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- A flat manifold Y with a locally expansive n-fold cover g determines two dynamical systems:
  - 1 The Wieler Solenoid  $\varprojlim(\textbf{Y},\textbf{g})$  with groupoid  $\mathcal{G}_u$
  - 2 The odometer  $\pi_1(\mathbf{Y}) \curvearrowright \varprojlim (\pi_1(\mathbf{Y})/g_*^{\mathbf{j}}(\pi_1(\mathbf{Y}),\mathbf{i}_{\mathbf{j}}^{\mathbf{j}+1})$  with groupoid  $\mathcal{G}_{\text{orbit}}$

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- Each solenoid admits a Markov Partition

$$\pi: (\{0,1,\ldots,n-1\}^{\mathbb{Z}} \cong (G/G_1)^{\mathbb{Z}},\sigma) \to \varprojlim(Y,g)$$

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### Theorem (Scarparo(special case) )

For Y flat, g a locally expansive n-fold cover, and  $\pi_1(Y) \curvearrowright \varprojlim \left(\pi_1(Y)/g_*^j(\pi_1(Y)), i_j^{j+1}\right)$  the associated odometer,

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#### **Theorem**

For Y an oriented flat d-manifold,

$$H_*(\mathcal{G}^u) \cong H^{d-*}(X)$$

Note: Doesn't hold when Y is not orientable

### Theorem (Scarparo, Baum-Connes, Carrión, Green, etc.)

Given Y flat, g a locally expansive d-fold cover, and  $\pi_1(Y) \curvearrowright \varprojlim \left(\pi_1(Y)/g_*^j(\pi_1(Y)), i_j^{j+1}\right)$  the associated odometer,

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• If Y is spin<sup>c</sup>:

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where  $g^*$  is the induced map on K-theory

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Then

$$K_*(C_r^*(\mathcal{G}^u)) \cong K_*(C_r^*(\mathcal{G}_{orbit})) \cong \varinjlim(K_*(Y), g!)$$

• If Y is spin<sup>c</sup>:

$$\operatorname{lim}(K_*(Y), g!) \cong \operatorname{lim}(K^{*+d}(Y), g^*),$$

where  $g^*$  is the induced map on K-theory

• Since  $X = \underline{\lim}(Y, g)$ :

$$K^{*+d}(X) \cong \underline{\lim}(K^{*+d}(Y), g^*).$$

### *K*-theory cont

#### Theorem

For Y a spin<sup>c</sup> flat n-manifold,

$$K_*(C_r^*(\mathcal{G}^u)) \cong K^{*+d}(X)$$

Doesn't hold in general when Y is not spin<sup>c</sup>